UTILITY PATENT APPLICATION TRANSMITTAL

(Only for new nonprovisional applications under 37 CFR 1.53(b))

Attorney Docket No.	**35.C7695 CONT. III**
First Named Inventor or Application Identifier	**KATSUMI AZUSAWA, ET AL.**
Express Mail Label No.	

APPLICATION ELEMENTS

See MPEP chapter 600 concerning utility patent application contents.

ADDRESS TO: Assistant Commissioner for Patents
Box Patent Application
Washington, DC 20231

1. [X] Fee Transmittal Form *(Submit an original, and a duplicate for fee processing)*
2. [X] Specification — *Total Pages* 25
3. [X] Drawing(s) *(35 USC 113)* — *Total Sheets* 5
4. [X] Oath or Declaration — *Total Pages* 2
   - a. [ ] Newly executed (original or copy)
   - b. [ ] Unexecuted for information purposes
   - c. [X] Copy from a prior application (37 CFR 1.63(d)) *(for continuation/divisional with Box 17 completed)* ***[Note Box 5 below]***
     - i. [ ] DELETION OF INVENTOR(S) Signed Statement attached deleting inventor(s) named in the prior application, see 37 CFR 1.63(d)(2) and 1.33(b).
5. [X] Incorporation By Reference *(useable if Box 4c is checked)* The entire disclosure of the prior application, from which a copy of the oath or declaration is supplied under Box 4c, is considered as being part of the disclosure of the accompanying application and is hereby incorporated by reference therein.
6. [ ] Microfiche Computer Program *(Appendix)*
7. Nucleotide and/or Amino Acid Sequence Submission *(if applicable, all necessary)*
   - a. [ ] Computer Readable Copy
   - b. [ ] Paper Copy (identical to computer copy)
   - c. [ ] Statement verifying identity of above copies

ACCOMPANYING APPLICATION PARTS

8. [ ] Assignment Papers (cover sheet & document(s))
9. [ ] 37 CFR 3.73(b) Statement *(when there is an assignee)* [ ] Power of Attorney
10. [ ] English Translation Document *(if applicable)*
11. [ ] Information Disclosure Statement (IDS)/PTO-1449 [ ] Copies of IDS Citations
12. [X] Preliminary Amendment & Information Disclosure Statement w/1449 and 1 reference
13. [X] Return Receipt Postcard (MPEP 503) *(Should be specifically itemized)*
14. [ ] Small Entity Statement(s) [ ] Statement filed in prior application Status still proper and desired
15. [ ] Certified Copy of Priority Document(s) *(if foreign priority is claimed)*
16. [ ] Other: _____

17. If a CONTINUING APPLICATION, *check appropriate box and supply the requisite information:*
    [X] Continuation [ ] Divisional [ ] Continuation-in-part (CIP) of prior application No. 08/380,336

18. CORRESPONDENCE ADDRESS

[X] Customer Number or Bar Code Label — 05514 (Insert Customer No. or Attach bar code label here) — or [ ] Correspondence address below

NAME					
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City		State		Zip Code	
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CLAIMS	(1) FOR	(2) NUMBER FILED	(3) NUMBER EXTRA	(4) RATE	(5) CALCULATIONS
	TOTAL CLAIMS (37 CFR 1.16(c))	15 -20 =	0	X $ 18.00 =	$00.00
	INDEPENDENT CLAIMS (37 cfr 1.16(b))	3 -3 =	0	X $ 78.00 =	$00.00
	MULTIPLE DEPENDENT CLAIMS (if applicable) (37 CFR 1.16(d))			$260.00 =	$00.00
				BASIC FEE (37 CFR 1.16(a))	$760.00
			Total of above Calculations =		$760.00
	Reduction by 50% for filing by small entity (Note 37 CFR 1.9, 1.27, 1.28).				
				TOTAL =	$760.00

19. Small entity status

a. ☐ A Small entity statement is enclosed

b. ☐ A small entity statement was filed in the prior nonprovisional application and such status is still proper and desired.

c. ☐ Is no longer claimed.

20. ☒ A check in the amount of $ 760.00 to cover the filing fee is enclosed.

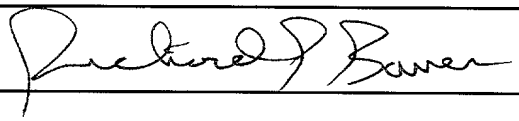
21. ☐ A check in the amount of $ _____ to cover the recordal fee is enclosed.

22. The Commissioner is hereby authorized to credit any overpayments or charge any deficiences to Deposit Account No. 06-1205:

a. ☒ Fees required under 37 CFR 1.16.

b. ☐ Fees required under 37 CFR 1.17.

c. ☐ Fees required under 37 CFR 1.18.

SIGNATURE OF APPLICANT, ATTORNEY, OR AGENT REQUIRED	
NAME	**RICHARD P. BAUER, REG. NO. 31,588**
SIGNATURE	
DATE	**July 20, 1999**

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35.C7695 CONT. III PATENT APPLICATION

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

In re Application of:	)	
	:	Examiner: T. Ho
KATSUMI AZUSAWA, ET AL.	)	
	:	Group Art Unit: 2712
Appln. No.: To be assigned	)	
	:	
Filed: July 20, 1999	)	
	:	
For: IMAGE PICKUP APPARATUS	)	July 20, 1999

Assistant Commissioner for Patents
Washington, D.C. 20231

PRELIMINARY AMENDMENT AND INFORMATION DISCLOSURE STATEMENT

Sir:

Prior to examination, kindly amend the above-identified application as follows:

IN THE TITLE:

Kindly amend the title to read --PICKUP DEVICE APPARATUS INCLUDING VIBRATION CORRECTION MEANS--.

IN THE SPECIFICATION:

Page 1

Line 8, after "have" delete "remarkably";

Line 9, after "become" insert --remarkably";

Line 12, after "most" delete "of";

Line 17, after "hand" insert --held--; and

Line 18, before "state" (first occurrence) delete "holding".

Page 2

Line 8, change "to locate" to --and thereby locating--; and

Line 21, after "in" insert --the--.

Page 6

Lines 9 and 10, after "operation" delete "performed while the image vibration correction mode is enabled"; and

Lines 21 and 22, after "operation" delete "performed while the image vibration correction mode is enabled".

Page 7

Lines 21 and 22, after "operation" delete "performed while the image vibration correction mode is enabled".

IN THE ABSTRACT OF THE DISCLOSURE:

Kindly delete the Abstract and replace it with the new Abstract of the Disclosure as follows:

--An image pickup apparatus includes an image pickup element for converting an optical image on a focal

plane into an electrical image signal and outputting the electrical image signal. A vibration sensor detects a vibration amount of an image pickup apparatus main body, and an optical axis decentering member is provided for decentering an optical axis to cause the optical image to coincide with a predetermined position on the focal plane of the image pickup element. A driving control circuit controls a decentering amount of the optical axis decentering member on the basis of a detection output from the vibration sensor, and a control circuit controls the driving control circuit so that the decentering member is operated if the image pickup element is outputting the electrical signal.--

IN THE CLAIMS:

Kindly cancel Claims 1-11 without prejudice.

Kindly add Claims 12-26 as follows:

--12. An image pickup apparatus comprising:

(a) image pickup means for converting an optical image on an image pickup plane into an electrical image signal, and outputting the electrical image signal;

(b) detection means for detecting a shake of said apparatus, and for outputting a detection output;

(c) correcting means for correcting a movement of the image caused by the shake on the basis of the detection output of said detection means; and

(d) control means for disenabling said correcting means in the case that said image pickup means is not converting the optical image into the electrical image signal and not outputting the electrical image signal.

13. Apparatus according to Claim 12, wherein said correcting means comprises a variable angle prism.

14. Apparatus according to Claim 12, further comprising monitor means for displaying the electrical image signal output from said image pickup means.

15. Apparatus according to Claim 14, wherein said monitor means comprises an electronic viewfinder.

16. Apparatus according to Claim 15, wherein, when no image is output to said electronic viewfinder, said control means moves said correcting means to a position where a decentering amount with respect to the optical axis becomes zero, and thereafter, disables further movement of the correcting means.

17. A video camera apparatus comprising:

(a) image pickup means for converting an optical image on an image pickup plane into an electrical image signal;

(b) detection means for detecting a shake of said apparatus;

(c) compensating means for compensating a movement of an image caused by the shake on the basis of an output of said vibration detection means;

(d) displaying means for converting the image signal output from said image pickup means into an image, and for displaying said image; and

(e) control means for disenabling said compensating means in the case that said image pickup means is not converting the optical image into the electrical image signal and not outputting the image signal to said displaying means.

18. Apparatus according to Claim 17, wherein said detection means physically detects a vibration of a body of the video camera.

19. Apparatus according to Claim 17, wherein said compensating means comprises a variable angle prism which varies an optical axis, and a drive circuit for driving said variable angle prism, and wherein said variable angle prism is disposed at a head portion of a lens optical system of the video camera body.

20. Apparatus according to Claim 17, wherein said control means automatically places said compensating means into an operation state when said detection means detects that vibration of a body of the video camera exceeds a predetermined level.

21. Apparatus according to Claim 17, wherein said control means turns off power of said compensating means when said image pickup means does not output an image pickup signal.

22. Apparatus according to Claim 17, wherein said displaying means comprises an electronic viewfinder arranged in the video camera.

23. A video camera control apparatus comprising:

(a) an image sensor for converting an optical image of an image pickup plane into an electrical image signal;

(b) detection means for detecting a relative movement between a video camera body and an object;

(c) compensating means for compensating the movement on the basis of an output of said movement detection means; and

(d) control means for disenabling said compensating means in the case that said image sensor is not

converting the optical image into the electrical image signals and not outputting the electrical image.

24. Apparatus according to Claim 23, wherein said detection means physically detects a vibration of a body of the video camera.

25. Apparatus according to Claim 23, wherein said compensating means comprises a variable angle prism which varies an optical axis, and a drive circuit for driving the variable angle prism, and wherein said variable angle prism is disposed at a head portion of a lens optical system of a body of the video camera.

26. Apparatus according to Claim 23, wherein said control means turns off power of said compensating means when said image sensor does not output an image pickup signal.--

REMARKS

Consideration and allowance of the subject application are respectfully requested.

Claims 12-26 are pending in the application. Claims 12, 17, and 23 are independent.

The title, abstract, and specification have been amended to correct minor, informal matters. No new matter has been added.

In view of the above amendments and remarks, it is believed that this application is now in condition for allowance, and a Notice thereof is respectfully requested.

INFORMATION DISCLOSURE STATEMENT

Sir:

In compliance with the duty of disclosure under 37 C.F.R. § 1.56 and in accordance with the practice under 37 C.F.R. §§ 1.97 and 1.98, the Examiner's attention is directed to the documents listed on the enclosed Form PTO-1449. Copies of U.S. Patent Nos. 5,012,270 and 5,117,246 have been furnished in prior U.S. Patent Appln. No. 07/928,099. A copy of U.S. Patent No. 5,596,366 is enclosed herewith.

CONCLUSION

It is respectfully requested that the above information be considered by the Examiner and that a copy of the enclosed Form PTO-1449 be returned indicating that such information has been considered.

Applicants' undersigned attorney may be reached in our Washington, D.C. office by telephone at (202) 530-1010.

All correspondence should continue to be directed to our below listed address.

Respectfully submitted,

Attorney for Applicants

Registration No. 31,588

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F501\W186870\dew

Image Pickup Apparatus

BACKGROUND OF THE INVENTION

Field of the Invention

The present invention relates to an image pickup apparatus such as a video camera.

Related Background Art

In recent years, video cameras have remarkably become popular since they have compact, lightweight structures, variable magnifications, and multifunctions.

In the above-mentioned video camera, most of functions associated with an image pickup operation are automated. Therefore, an unsuccessful image pickup operation caused by the functions of the video camera itself rarely occurs.

The video camera is most frequently used in a hand holding state. In this state, the frame may be considered to be always vibrated. In recent years, degradation of image quality caused by the frame vibration, and an uncomfortable situation such as "video sickness" are discussed as problems.

As a means for eliminating the above-mentioned frame vibration, an image stabilization device utilizing a gyro mechanism is conventionally known.

In this device, a lens barrel system is movably supported by a gyro mechanism to obtain a stable image.

However, this device makes the camera main body bulky, and also causes an increase in weight.

In recent years, an image pickup apparatus, which comprises an image vibration correction means comprising optical axis decentering means such as a variable angle prism for decentering an optical axis of an image pickup optical system according to a vibration of a camera to locate an optical image on a predetermined focal plane of an image pickup element, has been developed.

The variable angle prism has the following structure. That is, a liquid having a given refractive index is sealed in an accordion-like chamber having a bellows clamped between two transparent plates. The transparent plate on the object side is tilted by a driving mechanism comprising a magnetic circuit, thereby decentering a photographing optical axis.

In the above-mentioned apparatus, since the optical axis is decentered by the variable angle prism, a lens barrel system need not be moved, and increases in size and weight of the camera main body can be minimized. Thus, a good image can be obtained by effectively preventing an image vibration.

In the above-mentioned apparatus, since an image vibration correction is performed by tilting the transparent plate of the variable angle prism by the driving mechanism comprising the magnetic circuit,

power consumption is increased as compared to a normal photographing mode. Thus, a demand has arisen for efficient battery saving means.

In addition, the apparatus using the variable angle prism suffers from the following problem.

In the image pickup apparatus comprising the image vibration correction means, e.g., the optical axis decentering means such as the variable angle prism, when the image vibration correction mode is disabled during an image recording operation, a tilting state by the driving mechanism for driving the transparent plate is released, and a centering operation occurs. That is, the two transparent plates become parallel to each other due to liquidity of the liquid sealed between them.

For this reason, discontinuous finder images are formed, and a user may feel uneasy.

SUMMARY OF THE INVENTION

The present invention has been made to solve the conventional problems, and has as its first object to provide an image pickup apparatus which can effectively perform an image vibration correction, and can also effectively perform an efficient battery saving operation.

In order to achieve this object, according to a preferred aspect of the present invention, there is disclosed an image pickup apparatus comprising image

pickup means for converting an optical image on a focal plane into an electrical image signal, and outputting the electrical image signal, vibration detection means for detecting a vibration amount of an image pickup apparatus main body, optical axis decentering means for decentering an optical axis so as to cause the optical image to coincide with a predetermined position on the focal plane of the image pickup means, driving control means for controlling a decentering amount of the optical axis decentering means on the basis of a detection output from the vibration detection means, and control means for, when the image pickup means outputs the electrical image signal, controlling to permit a driving operation of the optical axis decentering means by the driving control means.

According to another preferred aspect of the present invention, there is disclosed an image pickup apparatus comprising image pickup means for converting an optical image on a focal plane into an electrical image signal, recording/reproduction means for recording the electrical image signal from the image pickup means, and reproducing the recorded signal, vibration detection means for detecting a vibration amount of an image pickup apparatus main body, optical axis decentering means for decentering an optical axis so as to cause the optical image to coincide with a predetermined position on the focal plane of the image

pickup means, driving control means for controlling a decentering amount of the optical axis decentering means on the basis of a detection output from the vibration detection means, and control means for, when the recording/reproduction means reproduces the recorded signal, stopping operations of the optical axis decentering means and the driving control means.

Thus, according to the present invention, when the image pickup means outputs the electrical image signal, control is made to permit a driving operation of the optical axis decentering means by the driving control means. When the recording/reproduction means reproduces the recorded signal, the operations of the optical axis decentering means and the driving control means are stopped. Thus, an image vibration correction can be effectively performed, and an efficient battery saving operation can also be effectively attained.

It is the second object of the present invention to provide an image pickup apparatus which can effectively perform an image vibration correction, and an efficient battery saving operation since it controls to permit a driving operation of the optical axis decentering means by the driving control means when the image pickup means outputs an electrical image signal, and stops operations of the optical axis decentering means and the driving control means when the

recording/reproduction means reproduces a recorded signal.

It is the third object of the present invention to solve the conventional problems, and to provide an image pickup apparatus which can effectively perform an image vibration correction, and can effectively prevent discontinuous images even when an image vibration correction mode is disabled during an image recording operation performed while the image vibration correction mode is enabled.

It is the fourth object of the present invention to provide an image pickup apparatus which can effectively perform an image vibration correction since it controls to hold an optical axis decentering position of optical axis decentering means when an optical axis decentering driving operation by the optical axis decentering means is stopped during an operation of a recording means, and can effectively prevent discontinuous images even when an image vibration correction mode is disabled during an image recording operation performed while the image vibration correction mode is enabled.

It is the fifth object of the present invention to provide an image pickup apparatus which can effectively perform an image vibration correction, and can effectively prevent formation of discontinuous monitor images as finder images even when an image vibration

correction mode is disabled during an image recording operation performed while the image vibration correction mode is enabled.

In order to achieve the above objects, according to still another preferred aspect of the present invention, there is disclosed an image pickup apparatus comprising image pickup means for converting an optical image on a focal plane into an electrical image signal, recording means for at least recording the electrical image signal from the image pickup means, vibration detection means for detecting a vibration amount of an image pickup apparatus main body, optical axis decentering means for decentering an optical axis so as to cause the optical image to coincide with a predetermined position on the focal plane of the image pickup means, driving control means for controlling a decentering amount of the optical axis decentering means on the basis of a detection output from the vibration detection means, and control means for, when an optical axis decentering driving operation by the optical axis decentering means is stopped during an operation of the recording means, controlling to hold an optical axis decentering position of the optical axis decentering means.

Other objects and features of the present invention will become apparent from the following

description taken in conjunction with the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a block diagram showing an arrangement of an image pickup apparatus according to the first embodiment of the present invention;

Fig. 2 is a block diagram for explaining in detail a variable angle prism, a vibration detecting sensor, and a VAP driving circuit shown in Fig. 1;

Fig. 3 is a flow chart for explaining an operation of a control circuit shown in Fig. 1; and

Figs. 4 and 5 are flow charts for explaining an operation of a control circuit according to the second embodiment of the present invention.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

Fig. 1 is a block diagram for explaining an image pickup apparatus according to an embodiment of the present invention.

In Fig. 1, the image pickup apparatus includes a VAP (Variable Angle Prism) 1 serving as an optical axis decentering means, and an image pickup optical system 2 including an image pickup lens 2a including a focusing lens, and an aperture stop 2b. The image pickup lens 2a is driven by a focus driving circuit 3, and the aperture stop 2b is driven by an iris driving circuit 4a and an iris control circuit 4b so as to control an

incident light amount of the image pickup optical system.

The apparatus also includes a CCD 5 as an image pickup element for photoelectrically converting an object image formed on a focal plane by the image pickup optical system 2 into an image pickup signal, and a camera process circuit 6 for executing predetermined processing, e.g., gamma correction, blanking processing, addition of a synchronization signal, and the like, of a video signal which is output from the CCD 5 and is amplified by a preamplifier (not shown), so as to convert the video signal into a standard television signal, and outputting the standard television signal from a video output terminal. The television signal output from the camera process circuit 6 is output to a video recorder section (not shown), and is also supplied to a monitor 7 such as an electronic viewfinder.

Furthermore, the apparatus includes an unfocused image width detecting circuit 8 for detecting an unfocused image width (width of an edge portion of an object image) of an object image from the video signal output from the CCD 5. The circuit 8 performs focus detection by utilizing a nature that an unfocused image width of an object is decreased as a focusing state approaches an in-focus state.

Moreover, the apparatus includes a control circuit 9 comprising, e.g., a microcomputer for controlling the entire system. The control circuit 9 comprises an I/O port, an A/D converter, a ROM, and a RAM. The control circuit 9 fetches unfocused image width data output from the unfocused image width detecting circuit 8, and peak value data of high-frequency components from a band-pass filter (not shown), and outputs a predetermined driving control signal to the focus driving circuit 3 to drive the image pickup lens 2a so that an unfocused image width in one field period of a video signal is minimized, and a peak value of high-frequency components is maximized. The control circuit 9 receives a detection signal from a vibration detecting sensor 10 for detecting a vibration amount of a video camera main body as the image pickup apparatus, and outputs a correction signal for correcting an optical axis in accordance with the vibration amount given by the detection signal, and an operation mode of the video camera main body to a VAP driving circuit 11. The VAP driving circuit 11 tilts the VAP 1 to decenter the optical axis, so that an optical image from the image pickup optical system 2 can be formed on a predetermined position of the focal plane of the CCD 5.

The VAP 1, the vibrating detecting sensor 10, and the VAP driving circuit 11 will be described in more detail below with reference to Fig. 2.

The vibration detecting sensor 10 has a structure as shown in Fig. 2. More specifically, a cylindrical case 12 is filled with a liquid 13 having a predetermined refractive index, and a float 14 which is rotatable about a predetermined rotational axis is arranged in the liquid 13. In a vibration free state, the float 14 is held at a predetermined position by a closed magnetic circuit constituted by a permanent magnet 15 arranged to surround the case 12. When the video camera main body is vibrated, and the float 14 is rotated relative to the case 12, signal light from a light-emitting element 16 is reflected by the surface of the float 14, and is incident on a light-receiving element 17 used for position detection. Therefore, the light incident position onto the light-receiving element 17 is changed depending on the position of the float 14, and an output signal is changed. The output signal from the light-receiving element 17 is output to the control circuit 9 via a position detecting circuit 18.

On the other hand, the VAP 1 has the following structure. That is, a liquid 23 having a predetermined refractive index is sealed in an accordion-like chamber 22 having a bellows clamped between two transparent plates 21a and 21b. The VAP 1 is arranged on the front surface side of the image pickup optical system 2 and the CCD 5. In accordance with an output from the

position detecting circuit 18 on the side of the vibration detecting sensor 10, a magnetic circuit 24 is driven by the VAP driving circuit 11 controlled by the control circuit 9, and the transparent plate 21a on the object side of the VAP 1 is tilted. The tilting amount of the transparent plate 21a is detected by detectors 25 and 26, and output signals from these detectors are output to the control circuit 9 via a position detecting circuit 27. The control circuit 9 controls the VAP driving circuit 11 to drive the magnetic circuit 24, thereby tilting the transparent plate 21a of the VAP 1, so that a difference between the output from the position detecting circuit 18 on the side of the vibration detecting sensor 10, and the output from the position detecting circuit 27 on the side of the VAP 1 becomes "0".

The operation of the control circuit 9 described above as the characteristic feature of the image pickup apparatus of the present invention will be described below with reference to the flow chart shown in Fig. 3.

It is checked if the video camera is set in a vibration prevention mode (step 1). If it is determined that the vibration prevention mode is set, it is then checked if the video camera is set in a reproduction mode (step 2). If it is determined that the reproduction mode is not set, it is checked if an image based on an image pickup signal from the CCD 5 is

output to the monitor 7 (e.g., in an REC pause or REC state) (step 3). If it is determined that the image is output to the monitor 7, the vibration prevention function is operated (step 4). More specifically, when a picked-up image can be output to the monitor 7, the vibration prevention function is enabled even when no image recording operation is performed.

If it is determined that no image based on an image pickup signal from the CCD 5 is output to the monitor 7, or if it is determined in step 1 that the vibration prevention mode is not set, and if it is determined in step 2 that the reproduction mode is set, the vibration prevention function is turned off (step 5).

Therefore, in this embodiment, when an image based on an image pickup signal from the CCD 5 is output to the monitor 7, the control circuit 9 controls to enable the driving operation of the VAP 1 via the VAP driving circuit 11. When the recorder (not shown) outputs a signal representing the reproduction mode to the control circuit 9, the control circuit 9 controls to stop the operations of the VAP 1 and the VAP driving circuit 11. As a result, an image vibration correction can be effectively performed, and an efficient battery saving operation can be effectively attained.

The above embodiment exemplifies a so-called TV-AF system (auto focus system using a television signal)

wherein focus detection is performed by utilizing the nature that an unfocused image width of an object is decreased as a focusing state approaches an in-focus state. However, this embodiment may be applied to an active AF system comprising a light-emitting element, and a light-receiving element.

In the above embodiment, an image vibration correction mechanism is integrally arranged in the video camera as the image pickup apparatus. However, the VAP, the vibration detecting sensor, the VAP driving circuit, and the control circuit may be separately arranged as an adapter detachable from the video camera main body. Furthermore, the control circuit may be used commonly by the video camera main body.

In the image pickup apparatus of the present invention, as described above, when an electrical image signal is output from an image pickup means, control is made to permit a driving operation of an optical axis decentering means by a driving control means. When a recording/reproduction means reproduces a recorded signal, the operations of the optical axis decentering means and the driving control means are stopped. Therefore, an image vibration correction can be effectively performed, and an efficient battery saving operation can be effectively attained.

The second embodiment of the present invention will be described below.

This embodiment discloses an image pickup apparatus which can prevent discontinuous and poor images from being output as finder images when an image vibration correction device is mounted on, e.g., a video camera, and an operation mode of the camera is changed.

This embodiment will be described below. The circuit arrangement of this embodiment, and a VAP, a vibration detecting sensor, and a VAP driving circuit as a vibration correction means are the same as those in the embodiment shown in Figs. 1 and 2, and a difference is only a control program of a control circuit 9 for controlling the overall apparatus.

The operation of the control circuit 9 as the characteristic feature of the image pickup apparatus of the present invention will be described below with reference to the flow charts shown in Figs. 4 and 5.

The VAP as the optical axis decentering means used in the video camera as the image pickup apparatus of the present invention can be used in a full auto mode of the video camera, and in a manual mode capable of turning on/off the vibration prevention function according to a user's will.

As shown in Fig. 4, when the full auto mode of the video camera is set, it is checked if the video camera

is set in an REC pause state (step 11). If it is determined that the REC pause state is set, it is checked if an output signal from the vibration detecting sensor 10 exceeds a predetermined value (step 12). If it is determined that the output signal exceeds the predetermined value, the VAP 1 is operated (step 13). It is then checked if the camera is set in an REC state (step 14). If it is determined that the REC state is set, an image recording state with the ON vibration prevention function in which the VAP 1 is operated is set. However, if it is determined that the REC state is not set, it is checked if the REC pause state is set (step 15). If it is determined that the REC pause state is set, the flow returns to step 2. If it is determined that the REC pause state is not set, a centering operation is performed, i.e., the tilting position of the transparent plate 21a of the VAP 1 which decenters the optical axis on the basis of a predetermined time constant is gradually returned to a centering position where the transparent plates 21a and 21b are parallel to each other (step 16). Upon completion of the centering operation, the vibration prevention function is turned off (step 17).

If it is determined in step 2 that the output signal from the vibration detecting sensor 10 is below the predetermined value, the tilting position of the VAP 1 is temporarily held (step 18). It is then

checked if the tilting position of the transparent plate 21a of the VAP 1 is offset from the center by a predetermined value or more (step 19). If it is determined that the tilting position is offset from the center, a centering operation is performed, i.e., the tilting position of the transparent plate 21a of the VAP 1 which decenters the optical axis is gradually returned to a centering position where the transparent plates 21a and 21b are parallel to each other (step 20). Upon completion of the centering operation, the flow returns to step 1.

Therefore, when the video camera is set in the full auto mode, if the video camera main body is vibrated by a predetermined value or more by, e.g., camera shake in the REC pause state wherein an optical image from the image pickup optical system is output to the monitor 7 as the viewfinder, the vibration prevention function is automatically operated. In a vibration prevention function unnecessary state, e.g., when a vibration by camera shake is stopped, the tilting position of the transparent plate 21a of the VAP 1 is temporarily held, and the centering operation is gradually performed. In this manner, when the vibration prevention function is switched between ON and OFF states, an image from the monitor 7 as the viewfinder does not give an uneasy feeling to a user since the centering operation of the VAP 1 is gradually

performed without immediately changing the optical axis.

The vibration prevention function in the manual mode will be described below with reference to the flow chart shown in Fig. 5.

As shown in Fig. 5, it is checked if the vibration prevention function (VAP mode) is selected (step 21). If it is determined that the VAP mode is selected, it is then checked if the camera is set in the REC pause state (step 22). If it is determined that the REC pause state is set, the VAP mode is enabled (step 23). If it is checked if the VAP mode is turned off (step 24). It is determined that the VAP mode is OFF, it is checked if the REC state is set (step 25). If it is determined that the REC state is set, the tilting position of the transparent plate 21a of the VAP 1 is temporarily held by the driving operation of the magnetic circuit 24 (step 26). Thereafter, it is checked if the REC pause state is set (step 27). If the REC pause state is released, it is checked if the tilting position of the transparent plate 21a of the VAP 1 is offset from the center by a predetermined value or more (step 28). If it is determined that the tilting position is offset from the center, a centering operation is performed, i.e., the tilting position of the transparent plate 21a of the VAP 1 which decenters the optical axis on the basis of the predetermined time

constant is gradually returned to a centering position where the transparent plates 21a and 21b are parallel to each other (step 29).

Therefore, in the vibration prevention function in the manual mode, even when the vibration prevention function is switched between ON and OFF states, an image from the monitor 7 as the viewfinder does not give an uneasy feeling to a user since the centering operation of the VAP 1 is gradually performed without immediately changing the optical axis.

In this manner, in the above embodiment, an image vibration by camera shake can be effectively corrected, and even when an image vibration correction function as the vibration prevention function is switched between ON and OFF states, an image on the monitor as the finder can be effectively prevented from being discontinuously formed.

The above embodiment exemplifies a so-called TV-AF system (auto focus system using a television signal) wherein focus detection is performed by utilizing the nature that an unfocused image width of an object is decreased as a focusing state approaches an in-focus state. However, this embodiment may be applied to an active AF system comprising a light-emitting element, and a light-receiving element.

In the above embodiment, an image vibration correction mechanism is integrally arranged in the

video camera as the image pickup apparatus. However, the VAP, the vibration detecting sensor, the VAP driving circuit, and the control circuit may be separately arranged as an adapter detachable from the video camera main body. Furthermore, the control circuit may be used commonly by the video camera main body.

As described above, according to the image pickup apparatus of the present invention, an image vibration correction can be effectively performed, and even when an image vibration correction mode is disabled during an image recording operation performed while the image vibration correction mode is enabled, monitor images as finder images can be effectively prevented from being discontinued.

WHAT IS CLAIMED IS:

1. An image pickup apparatus comprising:

(a) image pickup means for converting an optical image on a focal plane into an electrical image signal, and outputting the electrical image signal;

(b) vibration detection means for detecting a vibration amount of an image pickup apparatus main body;

(c) optical axis decentering means for decentering an optical axis so as to cause the optical image to coincide with a predetermined position on the focal plane of said image pickup means;

(d) driving control means for controlling a decentering amount of said optical axis decentering means on the basis of a detection output from said vibration detection means; and

(e) control means for, when said image pickup means outputs the electrical image signal, controlling to permit a driving operation of said optical axis decentering means by said driving control means.

2. An apparatus according to claim 1, wherein said optical axis decentering means comprises a variable angle prism.

3. An apparatus according to claim 1, further comprising:

monitor means for displaying the electrical image signal output from said image pickup means.

4. An apparatus according to claim 3, wherein said monitor means comprises an electronic viewfinder.

5. An apparatus according to claim 4, wherein when no image is output to said electronic viewfinder, said control means controls said driving control means to move said optical axis decentering means to a position where a decentering amount with respect to the optical axis becomes 0, and thereafter, disables said driving control means.

6. An image pickup apparatus comprising:

image pickup means for converting an optical image on a focal plane into an electrical image signal;

recording means for at least recording the electrical image signal from said image pickup means;

vibration detection means for detecting a vibration amount of an image pickup apparatus main body;

optical axis decentering means for decentering an optical axis so as to cause the optical image to coincide with a predetermined position on the focal plane of said image pickup means;

driving control means for controlling a decentering amount of said optical axis decentering means on the basis of a detection output from said vibration detection means; and

control means for, when an optical axis decentering driving operation by said optical axis decentering means is stopped during an operation of said recording means, controlling to hold an optical axis decentering position of said optical axis decentering means.

7. An apparatus according to claim 6, wherein when a recording operation of said recording means is stopped, said control means releases the held optical axis decentering position of said optical axis decentering means.

8. An apparatus according to claim 6, wherein said optical axis decentering means comprises a variable angle prism.

9. An image pickup apparatus comprising:

(a) image pickup means for converting an optical image on a focal plane into an electrical image signal;

(b) recording/reproduction means for recording the electrical image signal from said image pickup means, and reproducing a recorded signal;

(c) vibration detection means for detecting a vibration amount of an image pickup apparatus main body;

(d) optical axis decentering means for decentering an optical axis so as to cause the optical image to coincide with a predetermined position on the focal plane of said image pickup means;

(e) driving control means for controlling a decentering amount of said optical axis decentering means on the basis of a detection output from said vibration detection means; and

(f) control means for, when said recording/reproduction means reproduces the recorded signal, stopping operations of said optical axis decentering means and said driving control means.

10. An apparatus according to claim 9, wherein said optical axis decentering means comprises a variable angle prism.

11. An apparatus according to claim 9, wherein said control means locks a position of said optical axis decentering means during reproduction.

ABSTRACT OF THE DISCLOSURE

An image pickup apparatus includes

an image pickup element for converting an optical image on a focal plane into an electrical image signal, and outputting the electrical image signal,

a vibration sensor for detecting a vibration amount of an image pickup apparatus main body,

an optical axis decentering member for decentering an optical axis so as to cause the optical image to coincide with a predetermined position on the focal plane of the image pickup element,

a driving control circuit for controlling a decentering amount of the optical axis decentering member on the basis of a detection output from the vibration sensor, and

a control circuit for, when the image pickup element outputs the electrical image signal, controlling to permit a driving operation of the optical axis decentering member by the driving control circuit.

FIG. 1

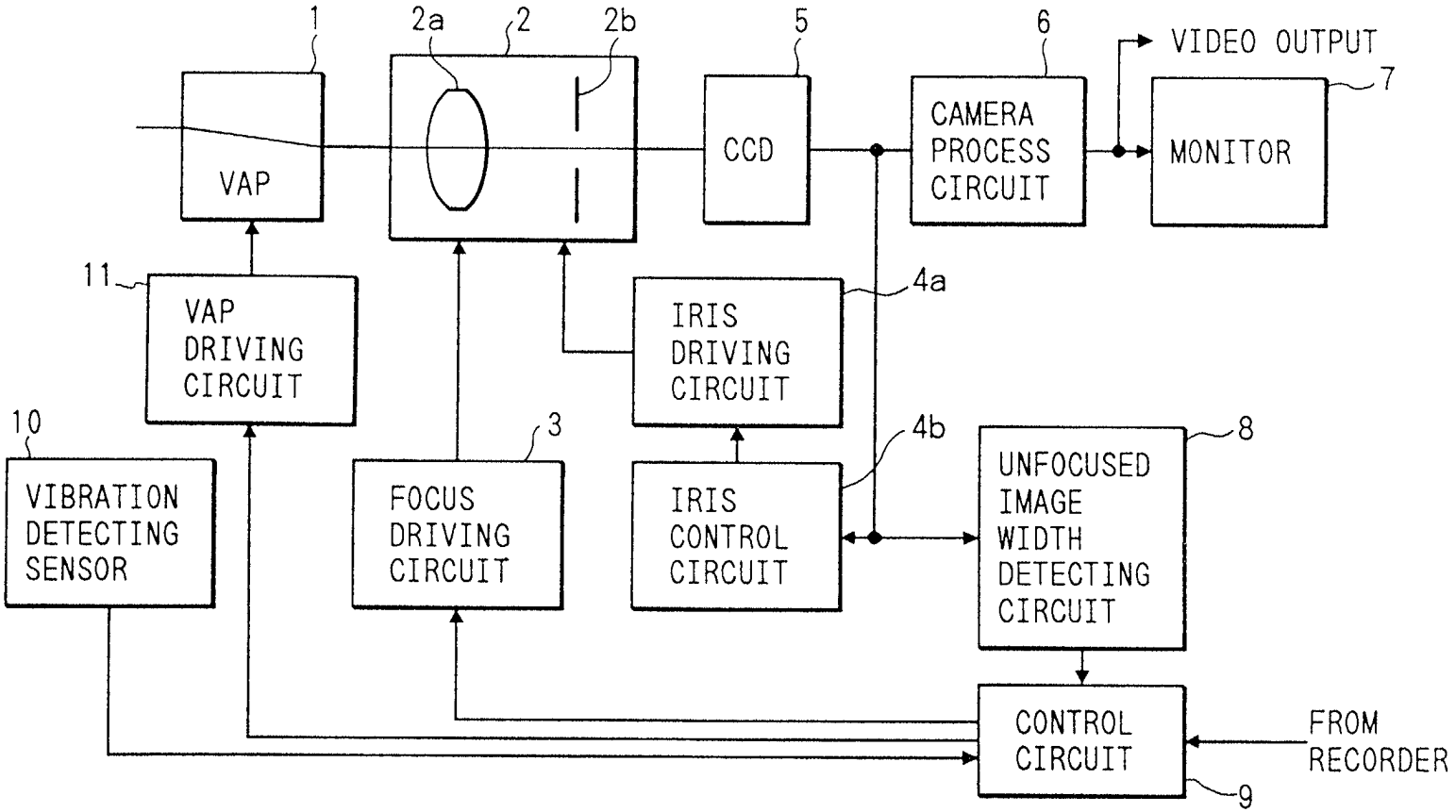

1
2a
2
2b
5
6
VIDEO OUTPUT
7
VAP
CCD
CAMERA PROCESS CIRCUIT
MONITOR
11
VAP DRIVING CIRCUIT
IRIS DRIVING CIRCUIT
4a
10
3
4b
8
VIBRATION DETECTING SENSOR
FOCUS DRIVING CIRCUIT
IRIS CONTROL CIRCUIT
UNFOCUSED IMAGE WIDTH DETECTING CIRCUIT
CONTROL CIRCUIT
FROM RECORDER
9

FIG. 2

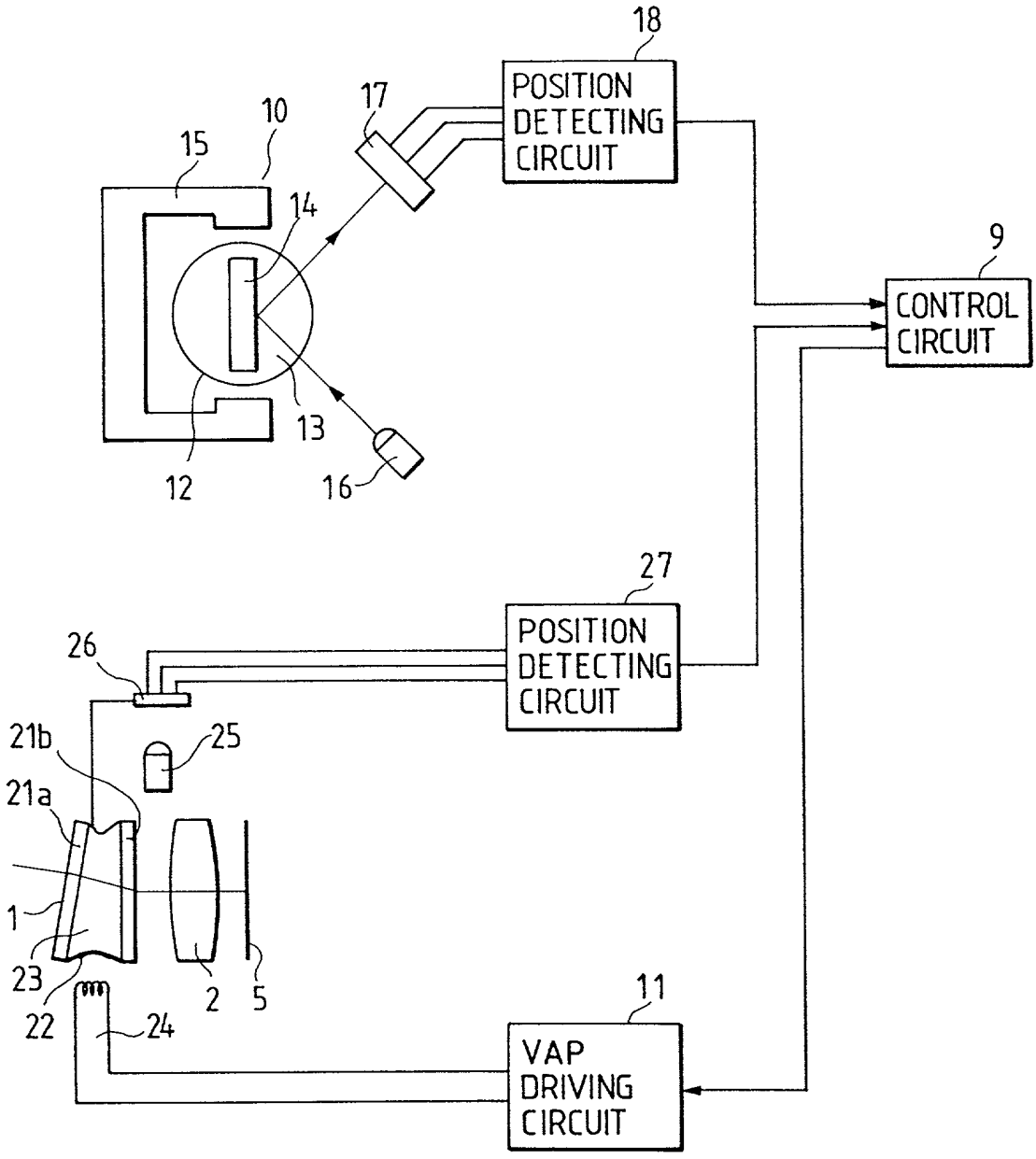

18
POSITION DETECTING CIRCUIT
17
10
15
14
9
CONTROL CIRCUIT
13
12
16
27
POSITION DETECTING CIRCUIT
26
21b
25
21a
1
23
22
24
2
5
11
VAP DRIVING CIRCUIT

FIG. 3

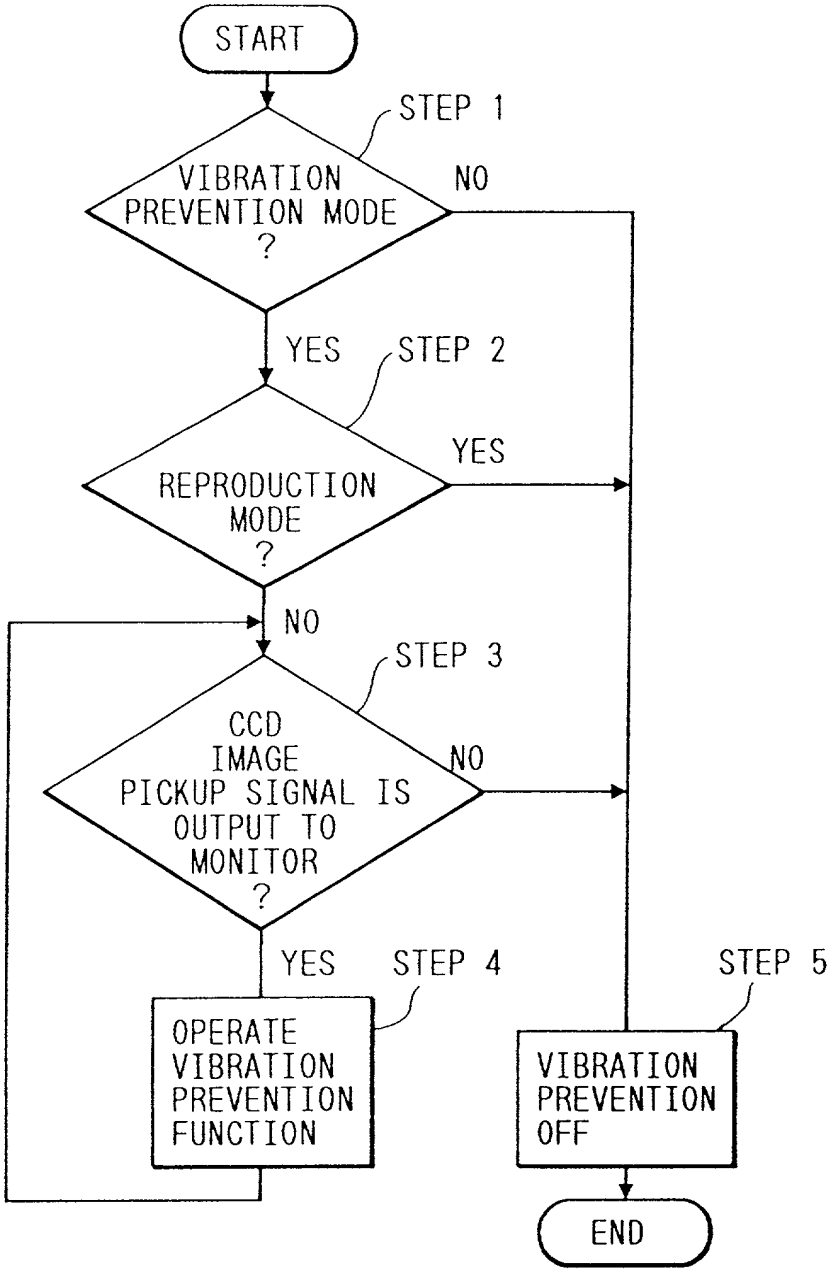

START
STEP 1
VIBRATION PREVENTION MODE ?
NO
YES
STEP 2
REPRODUCTION MODE ?
YES
NO
STEP 3
CCD IMAGE PICKUP SIGNAL IS OUTPUT TO MONITOR ?
NO
YES
STEP 4
OPERATE VIBRATION PREVENTION FUNCTION
STEP 5
VIBRATION PREVENTION OFF
END

FIG. 4

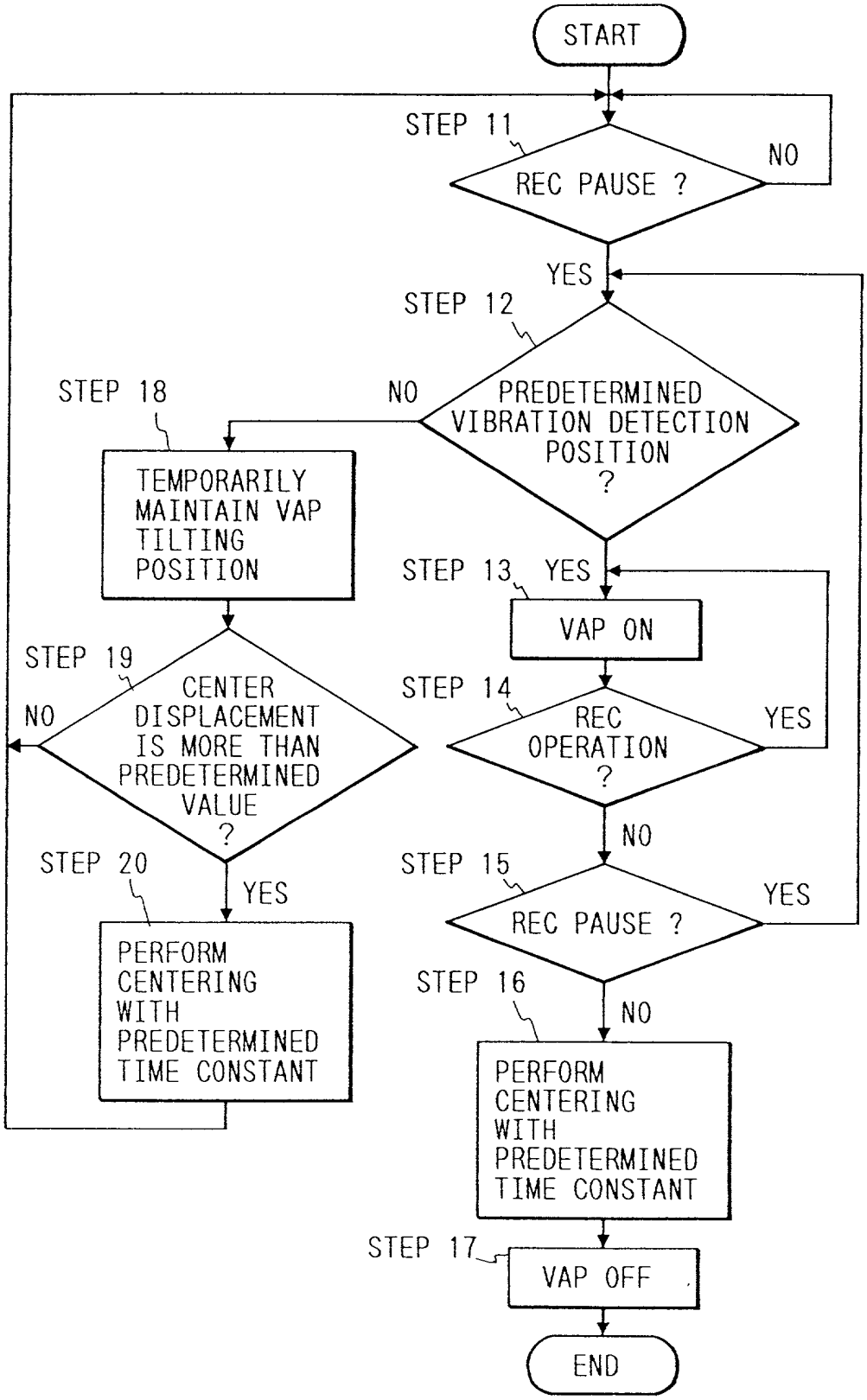
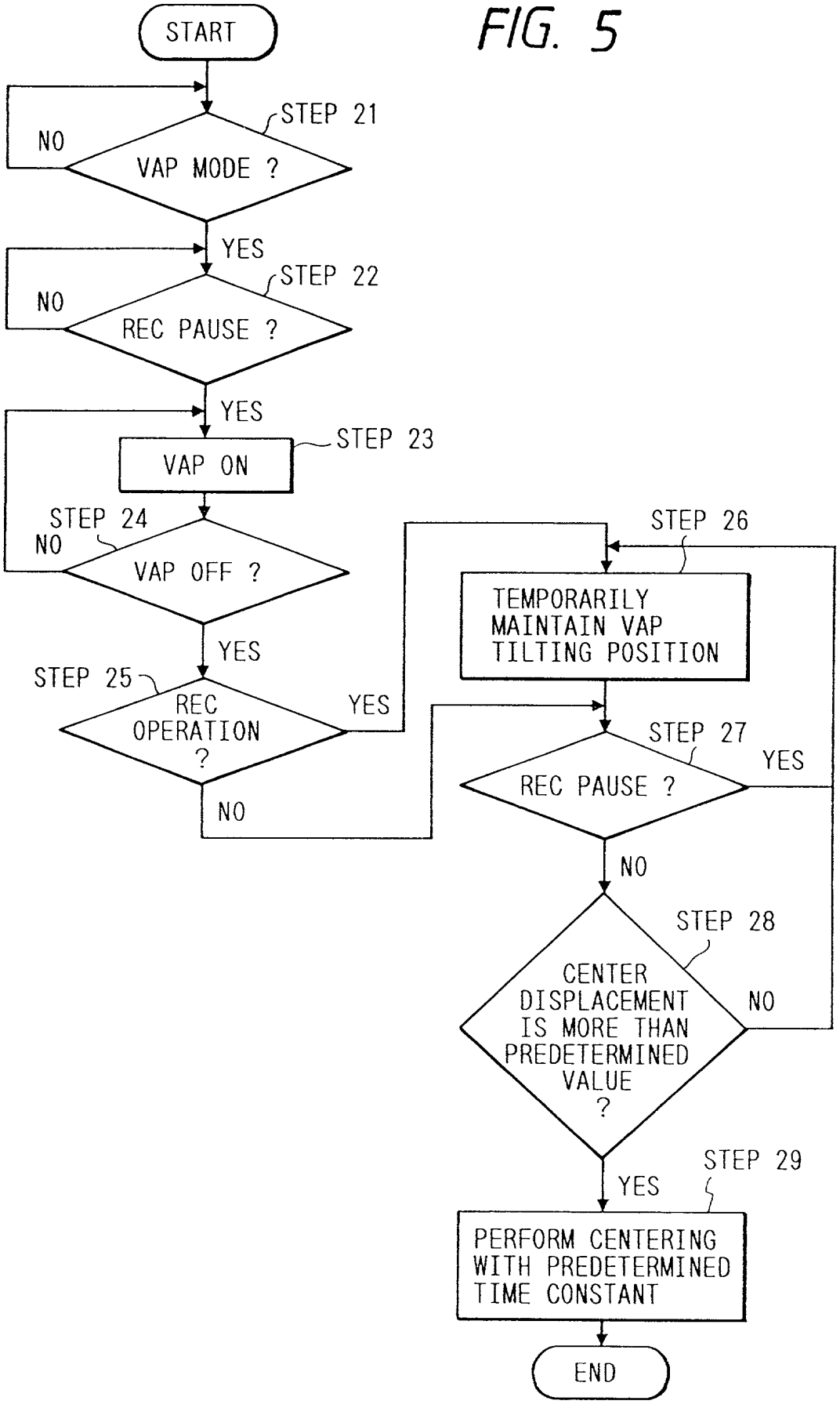

START
STEP 11
REC PAUSE ?
NO
YES
STEP 12
PREDETERMINED VIBRATION DETECTION POSITION ?
NO
STEP 18
TEMPORARILY MAINTAIN VAP TILTING POSITION
STEP 13
YES
VAP ON
STEP 14
REC OPERATION ?
YES
NO
STEP 15
REC PAUSE ?
YES
NO
STEP 16
PERFORM CENTERING WITH PREDETERMINED TIME CONSTANT
STEP 17
VAP OFF
END
STEP 19
CENTER DISPLACEMENT IS MORE THAN PREDETERMINED VALUE ?
NO
STEP 20
YES
PERFORM CENTERING WITH PREDETERMINED TIME CONSTANT

FIG. 5


START
STEP 21
NO
VAP MODE ?
YES
STEP 22
NO
REC PAUSE ?
YES
STEP 23
VAP ON
STEP 24
NO
VAP OFF ?
YES
STEP 25
REC OPERATION ?
YES
NO
STEP 26
TEMPORARILY MAINTAIN VAP TILTING POSITION
STEP 27
REC PAUSE ?
YES
NO
STEP 28
CENTER DISPLACEMENT IS MORE THAN PREDETERMINED VALUE ?
NO
YES
STEP 29
PERFORM CENTERING WITH PREDETERMINED TIME CONSTANT
END

COMBINED DECLARATION AND POWER OF ATTORNEY FOR PATENT APPLICATION

As a below named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name;

I believe I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled IMAGE PICKUP APPARATUS, the specification of which

[x] is attached hereto. [ ] was filed on _____ as Application Serial No. _____

and was amended _____ (if applicable).

I hereby state that I have reviewed and understand the contents of the above identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to the examination of this application in accordance with Title 37, Code of Federal Regulations, §1.56(a).

I hereby claim foreign priority benefits under Title 35, United States Code, §119 of any foreign application(s) for patent or inventor's certificate listed below and have also identified below any foreign application for patent or inventor's certificate having a filing date before that of the application on which priority is claimed:

Country	Application No.	Filed (Day/Mo./Yr.)	Priority Claimed (Yes/No)
JAPAN	2-161905	19 June 1990	Yes
JAPAN	2-171590	28 June 1990	Yes

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6 87

COMBINED DECLARATION AND POWER OF ATTORNEY FOR PATENT APPLICATION

(Page 2)

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

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